



# DIV PQ DIGITAL INTERFACE VALVE

DIGITAL INTERFACE VALVE WITH PROFIBUS  
INTERFACE

User Manual - Firmware DIV PQ

(B99225-DV010-BE400; Version 0.2, 10/07)

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**Completeness**

This document is complete only when used in conjunction with the product-related hardware and software documentation required for the relevant application, as for example operating instructions of the valve and other manuals.

**Selection and qualification of personnel**

As specified in the product-related hardware and software documentation required for the relevant application, only users properly qualified and authorized for these tasks may work with and on our products.

**Note**

This document has been prepared with great care in compliance with the relevant regulations, state-of-the-art technology and our many years of knowledge and experience, and the contents have been generated to the best of the authors' knowledge. However, the possibility of error remains and improvements are possible.

Please feel free to submit any comments about possible errors and incomplete information to us.

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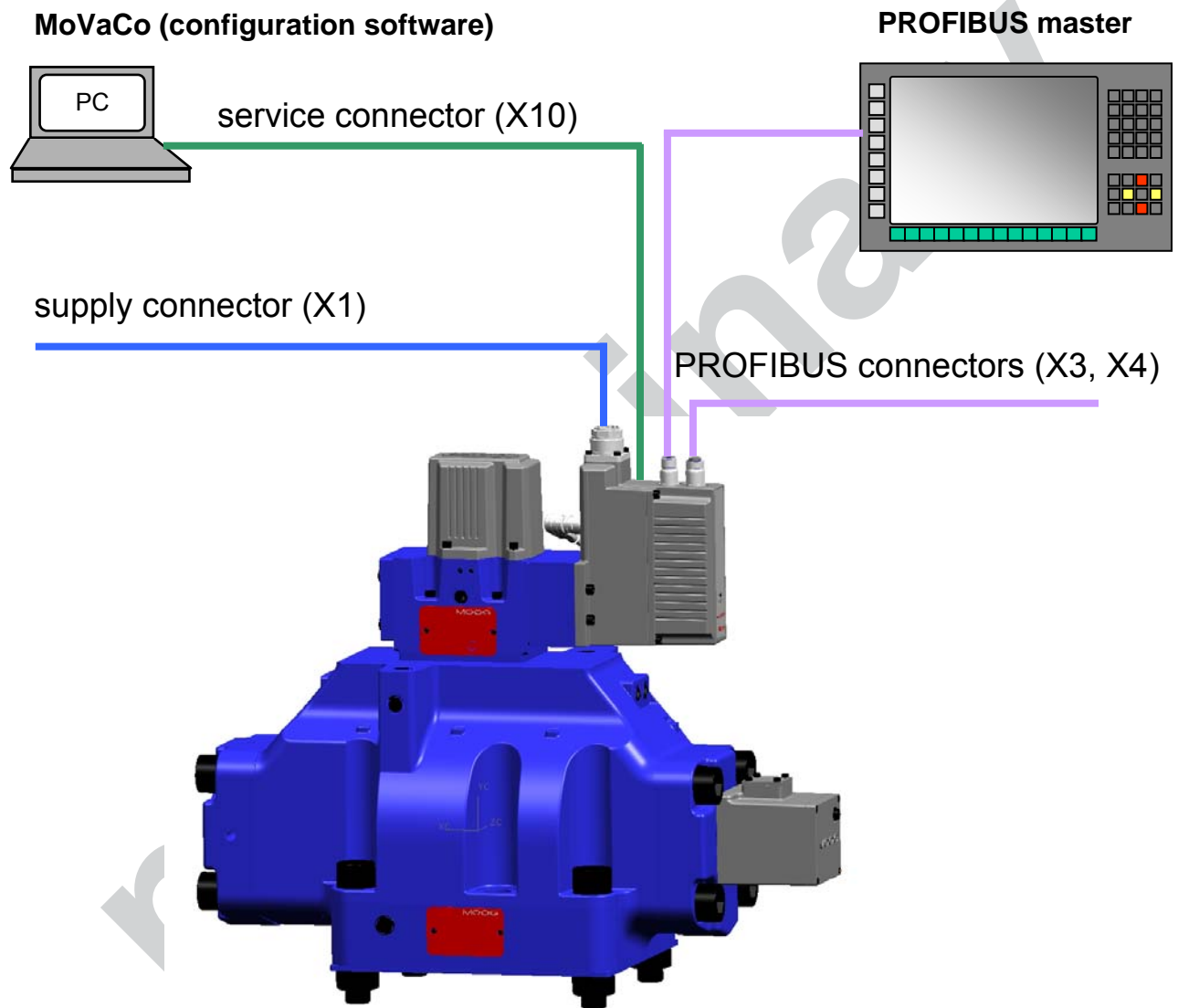
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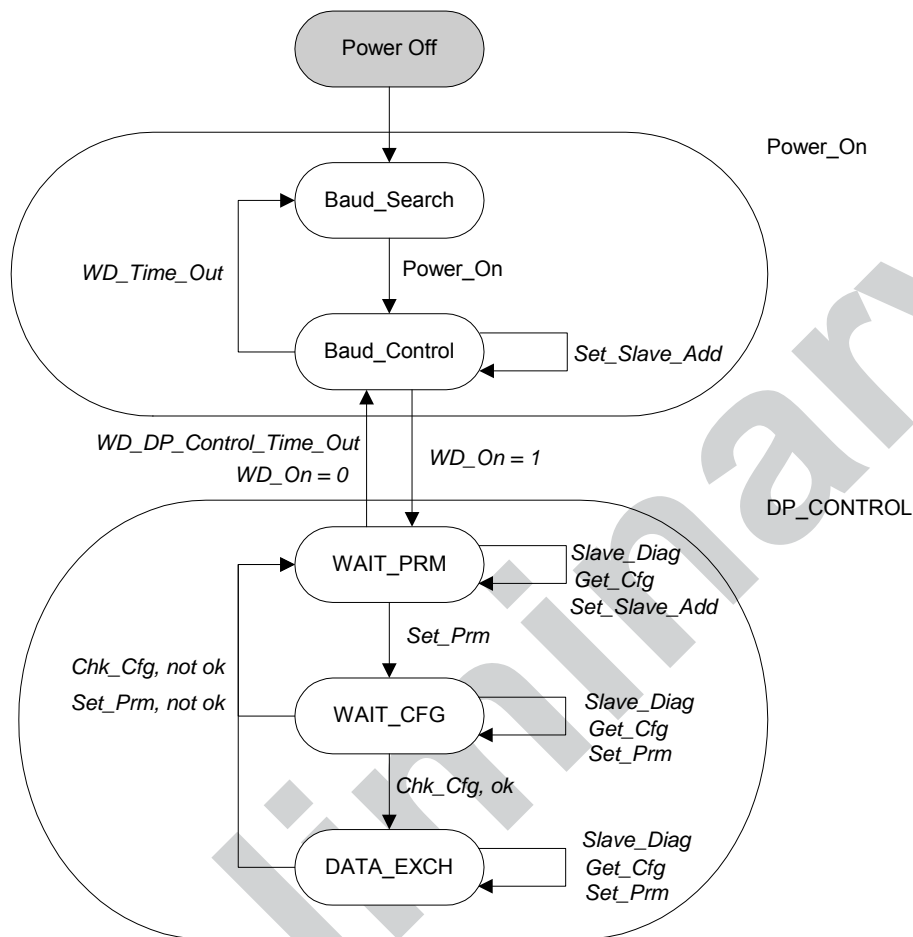
## 1 General Description

This specification describes the PROFIBUS DPV1 fieldbus interface for the DIV. The physical connectors as well as the profile specific parameters and telegrams necessary to built up a connection between the PLC and the valve.

The described functions and parameters are only a small extract from the existing ones. The complete functional specification is described in the PROFIBUS - DP Profile, Fluid Power Technology. Developed by the PROFIBUS Working Group „Fluid Power Technology“ based on the profiles developed by the VDMA e.V. Working Group „Fluid Power Technology“.



## 2 PROFIBUS state machine



### Power\_On

#### Baud\_Search:

The valve is capable of detecting the PROFIBUS baudrate set by the master automatically. When the electronic is in Baud\_Search state it can not accept any message. The electronic is searching for the transmission rate of the bus on different baudrates, trying to detect a correct SD1, SD2 or SD3 telegram. After identifying a baudrate the controller switches to Baud\_Control state.

#### Baud\_Control:

The detected baudrate is constantly monitored in the Baud\_Control state. Each error free detected telegram to its own station address resets the internal watchdog. The watchdog timer can be set by the user via the parameter telegram.

$$TWD = (1 \text{ ms or } 1 \text{ ms}) * WD\_FACT\_1 * WD\_FACT\_2$$

(see byte 7 of the "Set\_Prm" telegram)

If the watchdog expires the valve falls back to the Baud\_Search state and starts searching the bad-rate again. A watchdog time between 2 ms and 650 s – independent of the baudrate – can be implemented by using the watchdog factors.

Only in Power\_On state the slave accepts a Set\_Slave\_Address telegram.

**DP\_CONTROL:****WAIT\_PRM:**

After the startup phase the slave expects a parameter telegram which defines the behaviour of the slave. The parameter telegram contains for example information about the ident number, the sync/freeze capability, master address and watchdog time. In the state WAIT\_PRM the slave also accepts and responds to Get\_Cfg and Slave\_Diag telegrams. All other telegrams are ignored.

**WAIT\_CFG:**

The configuration telegram defines the number of input and output bytes. The master transmits the IO configuration to the valve. After receiving the Chk\_Cfg telegram the valve compares the configuration with its own configuration. If the configuration is acknowledged the valve confirms the configuration by setting the corresponding bit in the diagnosis state and enters automatically the DATA\_EXCH state and starts the cyclic communication with the master.

**DATA\_EXCH :**

If both Chk\_Cfg and Set\_Prm are confirmed positive the valve goes into DATA\_EXCH state and starts exchanging cyclic data with the master.

**Start up routine**

The ideal start up sequence for the before described telegrams is:

1. request diagnosis
2. changing station address (if necessary)
3. setting parameterization
4. checking configuration
5. request diagnosis (to check the preceeding commands)
6. data exchange

In parallel diagnosis requests, reparameterizations, reconfigurations and global control telegrams are accepted and processed by the valve.

**2.1 Status LEDs**

The valve's operating mode and the network status are displayed on multicolor light emitting diodes (status display LEDs) on the electronics housing.

**2.1.1 Module Status LED (MS)**

The Module Status LED displays operational and error states.

Module status LED (MS)	Condition
Off	No supply voltage
Green	normal operation
Blinking Green	Valve standby mode
Blinking red	Correctable error
red	unrecoverable error
Blinking red-green	Self-test

Table 1: Module Status (MS)

**2.1.2 Network Status LED (NS)**

The network status LED displays the status of the PROFIBUS network.

Network status LED (NS)	Condition
Off	No supply voltage
Green	state: "DATA_EXCH" valve is in data exchange state

Blinking Green	state: "WAIT_CFG" valve is waiting for configuration telegram
Orange	state: "WAIT_PRM" valve is waiting for parameter telegram
orange	State: "Baud_control" valve has detected baudrate
Blinking Orange	state: „Baud_Search“ valve is searching for correct baudrate
red	major error
Blinking red	Bus error
Blinking red-green	self-test

Table 2: Network Status (NS)

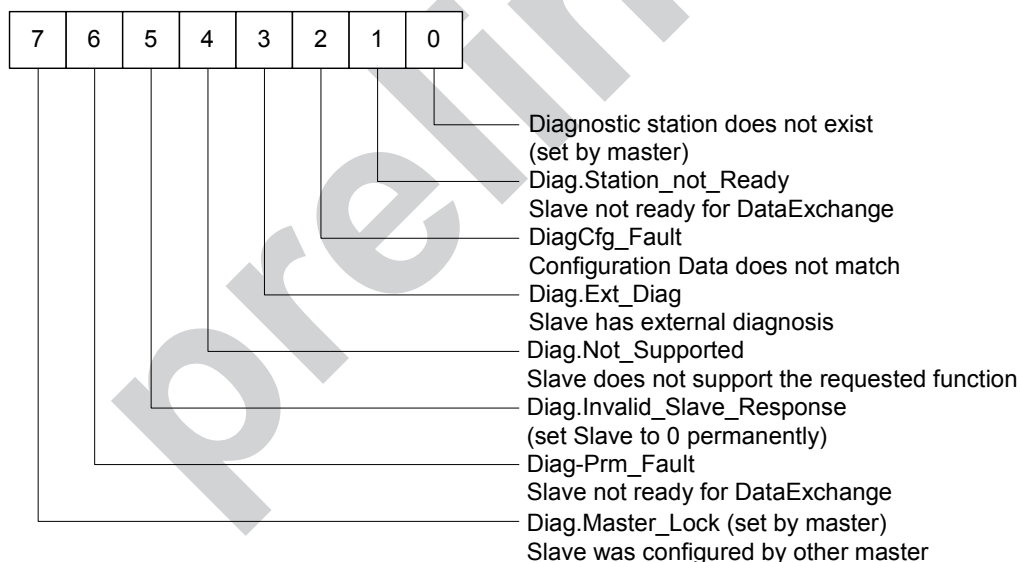
## 3 Master slave communication

### 3.1 Diagnosis

The diagnosis telegram is a high priority telegram which is send out on the request of the master. The diagnosis data can be read out at any time as soon as a stable connection baudrate is set up. During start up phase the master automatically fetches the diagnosis buffer (see startup routine). If new diagnostic data is available the valve indicates the After that the master requests in the next cycle a diagnosis telegram instead of a cyclic telegram. The diagnosis telegram contains 15 byte of status data. The first 7 bytes of the diagnosis data contain information according to the standard:

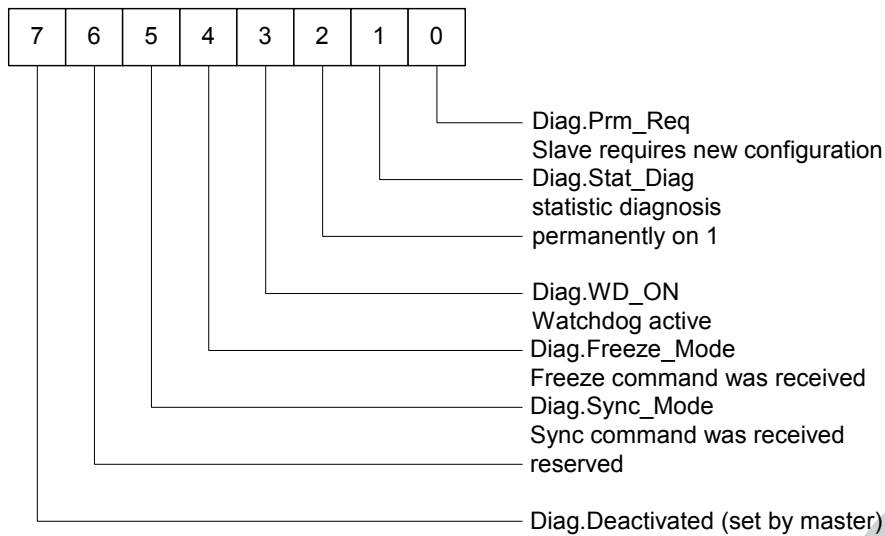
#### Byte 1:

Bit

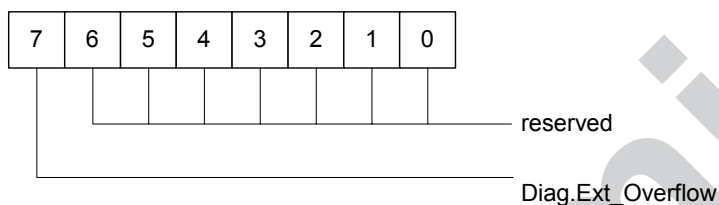


**Byte 2:**

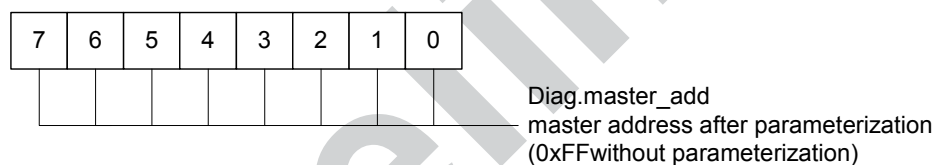
Bit

**Byte 3:**

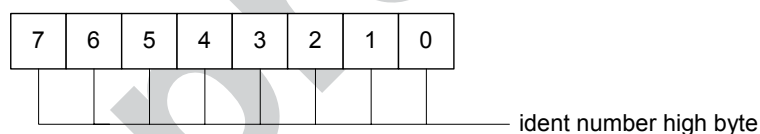
Bit

**Byte 4:**

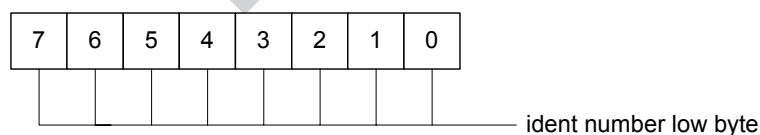
Bit

**Byte 5:**

Bit

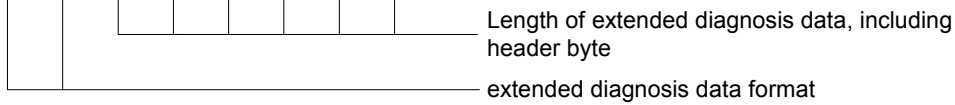
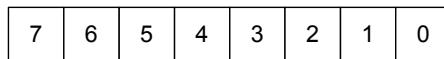
**Byte 6:**

Bit

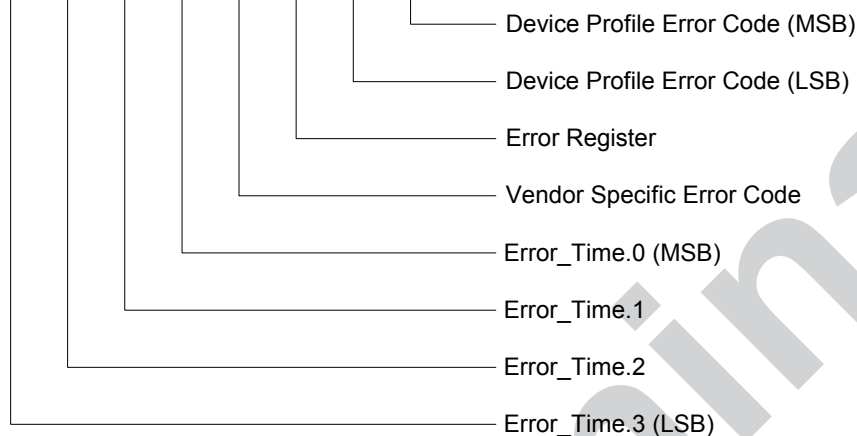
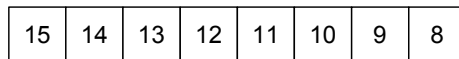


**Byte 7:**

Bit

**Byte 8 .. 15:**

Byte



The meaning of the “Device Profile Error Code” as well as the “Vendor Specific Error Code” are described in the following tables. The “Error Time” refers to the boot up time of the valve. It is measured in minutes. When the error is corrected, the valve acknowledges the new state with a cleared diagnosis telegram.

**Table of device profile error Codes:**

Profile Error Code	Description		
10xx	Generic Error		
20xx	Current		
21xx		Current, device input side	
2110		Input Current too high	
22xx		Current inside the device	
2211			Internal current #1
2212			Internal current #2
23xx		Current, device output side	
30xx	Voltage		
31xx		Mains Voltage	
3110			Input voltage out of range
32xx		Voltage inside the device	
3210			Internal voltage too high
3220			Internal voltage too low
33xx		Output Voltage	
3400		Internal voltage	
3410			Power supply voltage
3411			Power supply voltage too high
3412			Power supply voltage too low
3420		Control voltage	
3421			Control voltage too high
3422			Control voltage too low



40xx	Temperature		
41xx		Ambient Temperature	
4110			Ambient temperature too high
4120			Ambient temperature too low
42xx	Device Temperature		
4210		Temperature of electronic components	
4211			Temperature of electronic components too high
4212			Temperature of electronic components too low
4220		Temperature of hydraulic components	
4221			Temperature of hydraulic components too high
4222			Temperature of hydraulic components too low
50xx	Device Hardware		
5100		Hardware power supply	
5110			Internal power supply error
5200		Device control	
5210			Measurement circuits
5211			Pressure
5212			internal LVDT
5213			X1 Analog In #0
5214			X1 Analog In #1
5215			X5 Analog In #2
5216			X6 Analog In #3
5217			X7 Analog In #4
5218			X8 external LVDT
5220			Microprocessor core
5230			Sensors
5231			Pressure
5232			Encoder/SSI/Local CAN
5233			X1 Analog In #0
5234			X1 Analog In #1
5235			X5 Analog In #2
5236			X6 Analog In #3
5237			X7 Analog In #4
5238			X8 external LVDT
5300		Local input device	
5400		Power electronics	
5410			driver
5500		Data memory	
5510			RAM
5520			EPROM
5530			EEPROM
60xx	Device Software		
6010		Software reset (Watchdog)	
61xx		Internal Software	
6101			Error Handler
6102			Interrupt Time Exceeded
6103			Task Time Exceeded
6104			Out Of Memory
62xx		User Software	
6201			Event Handler
63xx		Data Set	
6310			Parameter loss
6311			Node Identifier Data
6312			User Data
6313			Restore Data
6314			Factory Data
6315			Calibration Data

6316			Diagnosis Data
6320		Parameter error	
70xx	Additional Modules		
7300	Sensor		
7310	Pressure sensor		
80xx	Monitoring		
8100		Communication	
8101		local CAN Communica- tion	
8102		CAN Overrun (Objects lost)	
8103		local CAN Overrun (Ob- jects lost)	
8104		CAN in Error Passive Mode	
8105		local CAN in Error Pas- sive Mode	
8106		Life Guard Error or Heartbeat Error	
8107		CAN recovered from bus off	
8108		local CAN recovered from bus off	
8109		CAN transmit COB-ID collision	
810A		local CAN Transmit COB- ID collision	
820B		Protocol Error	
820C		PDO not processed due to length error	
820D		PDO length exceeded	
8209		local RPDO1 time out	
820A		local RPDO2 time out	
820B		local RPDO3 time out	
820C		local RPDO4 time out	
820D		local TPDO1 time out	
820E		local TPDO2 time out	
820F		local TPDO3 time out	
8210		local TPDO4 time out	
8211		local RPDO1 data	
8212		local RPDO2 data	
8213		local RPDO3 data	
8214		local RPDO4 data	
8215		local TPDO1 data	
8216		local TPDO2 data	
8217		local TPDO3 data	
8218		local TPDO4 data	
825X		PROFIBUS	
8200		Closed loop control monitoring	
8201		Position control monito- ring	
8202		Pressure control monito- ring	
8203		Position Control	
8204		Velocity Control	
8205		Force Control	
8206		Flow Control	
8207		Current Control	
8208		Trajectory Generation	

Table 3: Profile Error Codes

Table of vendor specific error codes:

Additionally there is a vendor specific error code mapped into the diagnosis telegram of the valve which defines more detailed error conditions which are not covered by the profile codes.

Moog Error Code	Description
0	no_fault
1	error_microprocessor_core
2	error_digital_signal_processor
3	error_dsp_program_download
4	error_dsp_realtime_data_transmission
5	power_supply_voltage_too_low
6	power_supply_voltage_too_high
7	internal_supply_voltage_too_low
8	internal_supply_voltage_too_high
9	internal_reference_voltage_too_low
10	internal_reference_voltage_too_high
11	internal_current_too_low
12	internal_current_too_high
13	electronics_temperature_too_low (< -20degC)
14	electronics_temperature_too_high (> 85degC)
15	electronics_temperature_exceeded (> 105degC)
16	current_sensor_circuit_failure
17	pilot/single_stage_lvdt_cable_break
18	pilot/single_stage_lvdt_position_out_of_range
19	pilot/single_stage_lvdt_circuit_failure
20	main_stage_lvdt_cable_break
21	main_stage_lvdt_position_out_of_range
22	main_stage_lvdt_circuit_failure
23	internal_pressure_transducer_cable_break
24	internal_pressure_transducer_circuit_failure
25	internal_pressure_transducer_pressure_peak
26	analog_input_0:d_cable_break
27	analog_input_1:d_cable_break
28	analog_input_2:d_cable_break
29	analog_input_3:d_cable_break
30	analog_input_4:d_cable_break
31	analog_input_0:d_current_too_low (4-20mA)
32	analog_input_1:d_current_too_low (4-20mA)
33	analog_input_2:d_current_too_low (4-20mA)
34	analog_input_3:d_current_too_low (4-20mA)
35	analog_input_4:d_current_too_low (4-20mA)
36	analog_input_0:d_circuit_failure
37	analog_input_1:d_circuit_failure
38	analog_input_2:d_circuit_failure
39	analog_input_3:d_circuit_failure
40	analog_input_4:d_circuit_failure
41	encoder_channel_a_cable_break
42	encoder_channel_b_cable_break
43	encoder_channel_z_cable_break
44	ssi_error
45	power_driver
46	internal_random_access_memory
47	internal_program_memory
48	internal_nonvolatile_memory
49	out_of_memory_error
50	software_coding
51	software_reset (watchdog)
52	interrupt_time_exceeded
53	task_time_exceeded
54	parameter_initialisation_error
55	node_identifier_data_memory_corrupted
56	user_data_memory_corrupted
57	restore_data_memory_corrupted
58	factory_data_memory_corrupted
59	calibration_data_memory_corrupted
60	diagnosis_data_memory_corrupted
61	position_control_monitoring
62	velocity_control_monitoring
63	force_control_monitoring

64	flow_control_monitoring
65	pressure_control_monitoring
66	current_control_monitoring
67	spool_position_control_monitoring
68	trajectory_generator_processing_error
69	eventhandler_exception
70	local_CAN_general_fault
71	local_CAN_overrun
72	local_CAN_in_Error_passiv_mode
73	local_CAN_recovered_from_bus-off
74	local_CAN_rpdo_1;d_time_out
75	local_CAN_rpdo_2;d_time_out
76	local_CAN_rpdo_3;d_time_out
77	local_CAN_rpdo_4;d_time_out
78	local_CAN_rpdo_1;d_data
79	local_CAN_rpdo_2;d_data
80	local_CAN_rpdo_3;d_data
81	local_CAN_rpdo_4;d_data
82	local_CAN_tpdo_1;d_time_out
83	local_CAN_tpdo_2;d_time_out
84	local_CAN_tpdo_3;d_time_out
85	local_CAN_tpdo_4;d_time_out
86	local_CAN_tpdo_1;d_data
87	local_CAN_tpdo_2;d_data
88	local_CAN_tpdo_3;d_data
89	local_CAN_tpdo_4;d_data
90	CAN_general_fault
91	CAN_overrun
92	CAN_in_error_passiv_mode
93	CAN_recovered_from_bus-off
94	CAN_rpdo_1;d_time_out
95	CAN_rpdo_2;d_time_out
96	CAN_rpdo_3;d_time_out
97	CAN_rpdo_4;d_time_out
98	CAN_rpdo_1;d_data
99	CAN_rpdo_2;d_data
100	CAN_rpdo_3;d_data
101	CAN_rpdo_4;d_data
102	CAN_tpdo_1;d_time_out
103	CAN_tpdo_2;d_time_out
104	CAN_tpdo_3;d_time_out
105	CAN_tpdo_4;d_time_out
106	CAN_tpdo_1;d_data
107	CAN_tpdo_2;d_data
108	CAN_tpdo_3;d_data
109	CAN_tpdo_4;d_data
110	CAN_life_guard_error_or_heartbeat_error
111	CAN_sync_producer_time_out
112	CAN_sync_consumer_time_out
113	EtherCAT_communication_fault
114	EtherCAT_rpdo_time_out
115	EtherCAT_rpdo_data
116	EtherCAT_tpdo_time_out
117	EtherCAT_tpdo_data
118	PROFIBUS_general_fault

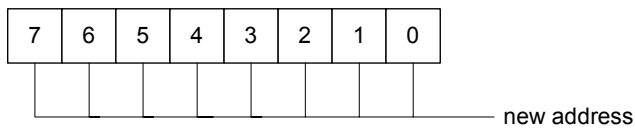
Table 4: Moog Error Codes

### 3.2 Changing station address

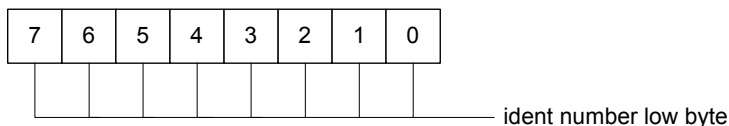
The factory setting for the PROFIBUS station address is by default 126. There are two possibilities to change the station address:

1. By sending the Set\_Slave\_Add telegram to the slave. The 4 data bytes of the telegram contain the new address, the identifier number and the flag whether the station address can be changed again. The identifier number of our digital interface valves is: 0x07F4. The “no address change” flag is cleared after a new boot up of the valve.

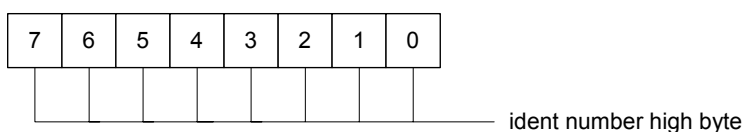
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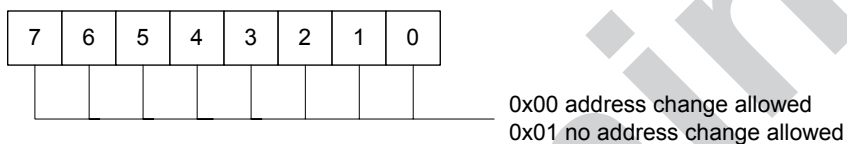
Bit



Bit



Bit



2. By writing on the “PROFIBUS module identifier” parameter.

The difference is that by using the Set\_Slave\_Add telegram the ID is changed immediately. When changing the value of the module identifier (e.g., over the parameter channel, or via the service interface) the new station address must then be saved through the “store/restore” routines and is used on the next boot up of the valve.

Slot	Index	Name	Data Type	Access	Persis- tence	Value Range	Default
64	0	PROFIBUS module ID	UINT08	rw	Y	1 .. 126	126

The node ID which can be read out through the service connector or over the PROFIBUS gives back the actual mode ID of the valve. If the module ID is changed over the PROFIBUS telegram the node ID is immediately changed. If the module ID is changed over parameter access the node ID still holds the actual module ID until the next boot up of the slave.

Slot	Index	Name	Data Type	Access	Persis- tence	Value Range	Default
64	33	PROFIBUS node ID	UINT08	rw	N	1 .. 126	126

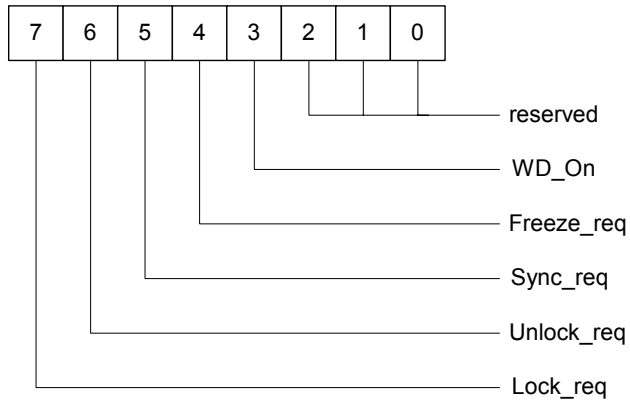
Because all slaves have the factory setting station number 126 it is recommended to install the valves one by one and configure the station address or to switch them on in a sequence because then the PLC can establish a peer to peer connection to the slave to configure the node ID. If more than one new valve is put into the bus with the ID 126 the PLC can not identify that there is more than one unconfigured slave. It is also possible to preconfigure the valves over the service connector before installing them in the PROFIBUS.

### 3.3 Parameter telegram

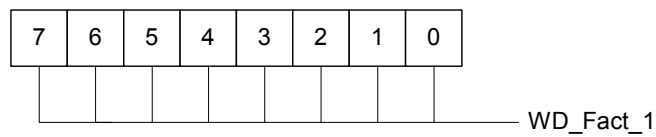
With the parameter telegram the master identifies itself and defines in which mode the slave will be operated, e.g., which global control commands will be accepted by the slave.

**Byte 1:**

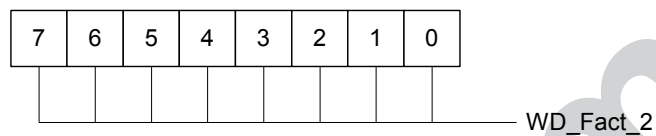
Bit

**Byte 2:**

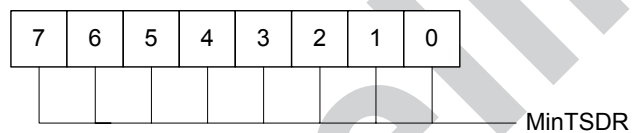
Bit

**Byte 3:**

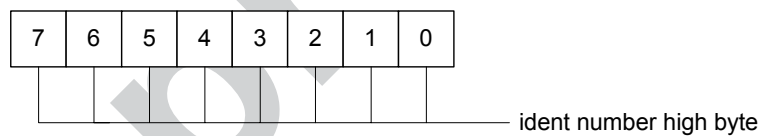
Bit

**Byte 4:**

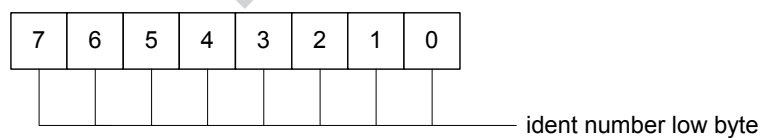
Bit

**Byte 5:**

Bit

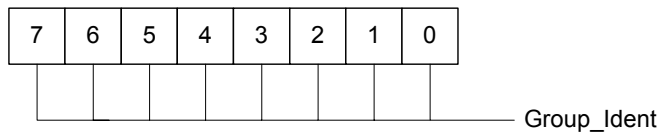
**Byte 6:**

Bit

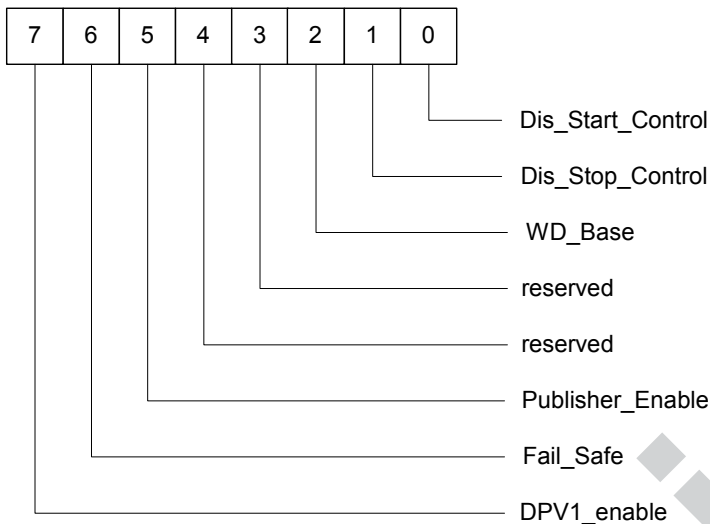


**Byte 7:**

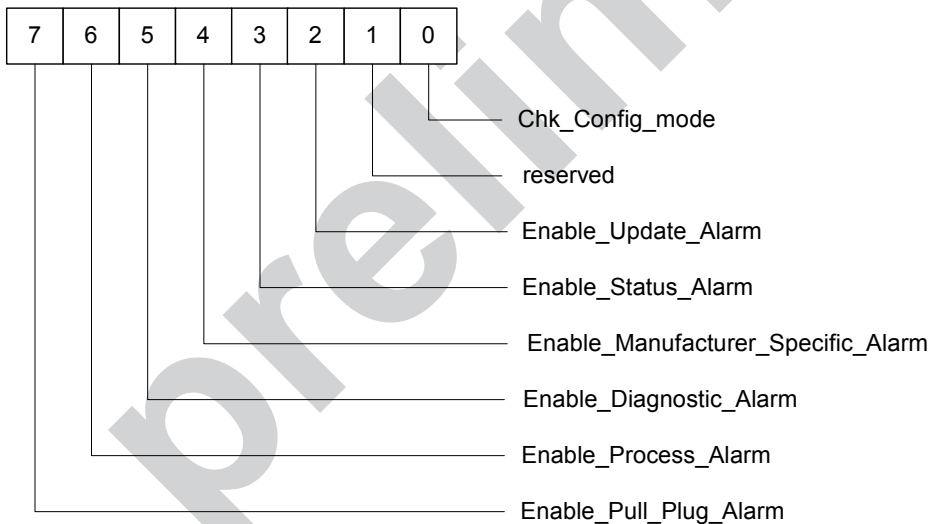
Bit

**Byte 8:**

Bit

**Byte 9:**

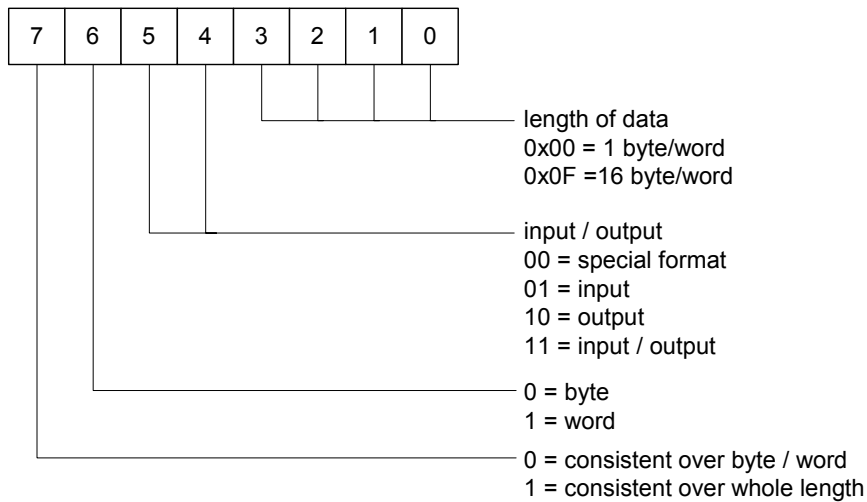
Bit

**3.4 Configuration telegram**

After the parameterization the master sends a configuration telegram to the slave. The slave checks the configuration of the master with its own and confirms or rejects the telegram. In one byte of the data unit of the telegram up to 16 bytes or words can be described. The signature of configuration which use the parameter channel contains the configuration byte 0xF3 (simultaneous in and out data, 4 words, full length consistency).

**All bytes of the configuration telegram have the following coding:**

Bit



Because there are many possibilities of coding the same input/output configuration it is necessary to use the coding the valve has calculated on the PLC. Otherwise the configuration from the PLC will be rejected.

The valve provides multiple predefined communication telegram configurations. To choose which telegram to use the parameter "TelegramSelection" has to be set to the right value.

Slot	Index	Name	Data Type	Access	Persis- tence	Value Range	Default
0	46	PROFIBUS telegram selector	UINT08	ro	Y	UINT08	3

Table of standardized and predefined telegrams:

Telegram	Description	Parameter Map- ping	Configuration	Meaning
0	User defined telegram	...	...	...
1	drives + par chn	Out : Par Chn Control word Position Setpoint In: Par chn Status word Position Value	0xF3,0xE2,0xD2	4 words input/output 3 words output 3 words input
2	drives	Out : Control word Position Setpoint In: Status word Position Value	0xE2,0xD2	3 words output 3 words input
3*	valves Q + par chn	Out : Par Chn Control word Spool Setpoint In: Par chn Status word Spool Value	0xF3,0xE1,0xD1	4 words input/output 2 words output 2 words input
4	valves Q	Out : Control word Spool Setpoint In: Status word Spool Value	0xE1,0xD1	2 words output 2 words input
5	valves p/Q + par chn	Out : Par Chn Control word	0xF3,0xE2,0xD2	4 words input/output 3 words output 3 words input



		Spool Setpoint Pressure Setpoint In: Par chn Status word Spool Value Pressure Value		
6	valves p/Q	Out : Control Word Spool Setpoint Pressure Setpoint In: Status Word Spool Value Pressure Value	0xE2,0xD2	3 words output 3 words input
100	valves p + par chn	Out : Par Chn Control word Spool Setpoint Pressure Setpoint In: Par chn Status word Spool Value Pressure value	0xF3,0xE1,0xD1	4 words input/output 2 words output 2 words input
101	valves p	Out : Control word Pressure Setpoint In: Status word Pressure Value	0xE1,0xD1	2 words output 2 words input

Table 5: Telegram Description

\*Telegram number 3 is the factory default configuration.

When the “user defined telegram” is used the valve automatically calculates the needed PROFIBUS configuration while the telegrams are put together. The number of configuration bytes and the configuration bytes can read out from the valve. After changing the parameter “Telegram Selection” the valve automatically calculates the new configuration which will be active after the next boot up. To find out which configuration has been calculated the number of relevant configuration bytes can be read out from the parameter “PROFIBUS configuration length”. The GSD-file which is delivered with the valve already contains the configurations for the standard telegrams.

Slot	Index	Name	Data Type	Access	Persis- tence	Value Range	Default
64	2	PROFIBUS configuration length	UINT08	ro	Y	UINT08	-

After reading out the number of configuration bytes the coding of this bytes can be looked up in the parameters which define the input or output configuration:

Slot	Index	Name	Data Type	Access	Persis- tence	Value Range	Default
64	3 .. 9	PROFIBUS input/output configuration	UINT08	rw	N	UINT08	-

#### User defined Telegram

If a user defined telegram is used the standard signals described in the profile can be used. If other parameters shall be transmitted cyclically over the PROFIBUS they have to be named in the following parameters

Slot	Index	Name	Data Type	Access	Persis- tence	Value Range	Default
64	17 .. 32	PROFIBUS signal parameter 1 .. 16	INT32	rw	N	INT32	0

By assigning the parameters to the “PROFIBUS signal parameters” 1 ..16 they are automatically assigned to the signal 240 .. 255. These Signals can now be assigned to the profile conform parameters which define the cyclic telegram.

#### Master to Slave Telegram Project MSB:

This parameter can contain up to four signal numbers which stand for the parameters which are transmitted from the master to the slave.

Slot	Index	Name	Data Type	Access	Persis- tence	Value Range	Default
0	42	Master to Slave Telegram Project MSB	INT32	rw	N	INT32	0

#### Master to Slave Telegram Project LSB:

This parameter can contain up to four signal numbers which stand for the parameters which are transmitted from the master to the slave.

Slot	Index	Name	Data Type	Access	Persis- tence	Value Range	Default
0	43	Master to Slave Telegram Project LSB	INT32	rw	N	INT32	0

#### Slave to Master Telegram Project MSB:

This parameter can contain up to four signal numbers which stand for the parameters which are transmitted from the slave to the master.

Slot	Index	Name	Data Type	Access	Persis- tence	Value Range	Default
0	44	Slave to Master Telegram Project MSB	INT32	rw	N	INT32	0

#### Slave to Master Telegram Project LSB:

This parameter can contain up to four signal numbers which stand for the parameters which are transmitted from the slave to the master.

Slot	Index	Name	Data Type	Access	Persis- tence	Value Range	Default
0	45	Slave to Master Telegram Project LSB	INT32	rw	N	INT32	0

#### PROFIBUS parameter channel activation:

The parameter is used to define whether the parameter channel shall be activated in the user defined telegram.

Slot	Index	Name	Data Type	Access	Persis- tence	Value Range	Default
64	10	PROFIBUS parameter channel activation (proprmchn)	UINT08	rw	Y	0 .. 1	0

### 3.5 Global control

The valves have the possibility to read and process global control telegrams. With the functions of this telegrams it is possible to “SYNC” the set command values to the valve while the valve continues operating. The valve uses the last set command to control the system, this gives the PLC the time and possibility to update the set commands of the whole application. With the “UNSYNC” function the PLC frees the new set command to the valve which starts controlling from this time with the set command. This is needed to synchronize groups of valves to the same set command or to get a system image of actual values.

Supported Global Control Commands:

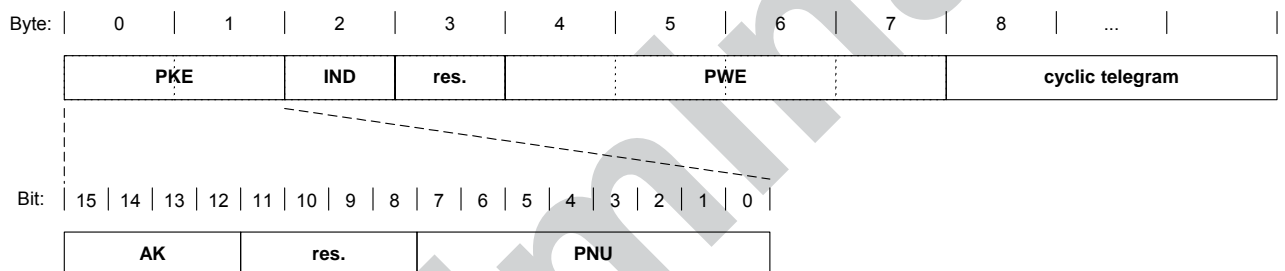
- SYNC
- UNSYNC
- FREEZE
- UNFREEZE

### 3.6 Parameter channel

There is the possibility to add a mechanism to configure parameters on the valve called the “parameter channel”. This mechanism adds 8 additional bytes of data into the input as well as the output telegram which are reserved for the transfer of parameters from master to slave or vice versa. The first 4 bytes are used to code the request or the response, the next 4 bytes contain the parameter data or in case of an transmission error the error code which is set by the slave.

Through this channel most of the parameters on the valve can be accessed, the only restriction of this mechanism is that the data to be send must consist of maximum four bytes. Thus makes it impossible to transfer arrays or look up tables.

The following schematic shows a cyclic telegram with the 8 additional bytes for the parameter channel communication. The coding for input and output telegram are equal. Only the interpretation of the command and value bytes differs between input and output.



- **PKE:** Parameter signature value.
- **IND:** Defines the index within the specified slot.
- **res.** Reserved bits or bytes (must be zero!).
- **PWE:** Process value.
- **AK:** Instruction/response signature (see following coding table).
- **PNU:** Parameter number (slot number of the parameter).

The complete coding of the parameter channel is conform to the parameter channel which is described in the “Fluid Power Technology” profile and the “ProfiDrive” profile (V2.0)

Commands (AK):

Signature	Function	Positive	Negative
0	No instruction	0	7
1	Parameter value read	1, 2, 11	7
2	Parameter value write (word)	1	7
3	Parameter value write (double word)	2	7
4 .. 9	reserved		
10	Parameter value write (byte)	11	7

Table 6: Parameter Channel Commands

Response commands (AK):

Signature	Function
-----------	----------

0	No Response
1	Parameter value transmitted (word)
2	Parameter value transmitted (double word)
3 .. 6	Reserved
7	Instruction not processable (see error code)
8 .. 10	reserved
11	Parameter value transmitted (byte)

Table 7: Parameter Channel Response

If the valve is not capable of processing the request from the PLC or the coding of the parameter channel is not correct the valve respond with an error code in the data section of the parameter channel instead of the requested value or zero value in case of an write command.

Table of error codes (PWE):

Error Code	Semantic
0	undefined PNU
1	Parameter not changeable
2	Lower or upper value range limit overflow
3	Subindex error
4	No array
5	Data type error
6	Setting not allowed (only resettable)
7	Description element not changeable
8	reserved
9	reserved
10	Access group error
11	No operation sovereignty
12	password error
13	Text not readable in cyclic data transfer
14	Name not readable in cyclic data transfer
15	No text array existent
16	reserved
17	Instruction not processable caused by bad operation state
18	other errors
19	Data not readable in cyclic error
20 .. 100	reserved for all PNO profiles
101 .. 200	reserved for future profile extensions
210 .. 255	vendor specific

Table 8: Parameter Channel Error Codes

## 4 Store/Restore

It is possible to save the changes of configuration inside a non volatile memory area of the electronic.

### 4.1 Store

To save the configuration changes a write access to the function "StoreParameters" has to be performed.

Slot	Index	Name	Data Type	Access	Persistence	Value Range	Default
------	-------	------	-----------	--------	-------------	-------------	---------

0	51	Store Parameters	INT32	rw	N	INT32	0
---	----	------------------	-------	----	---	-------	---

Value table:

Value	Function
0x73617665 ('save')	"StoreParameters" function is called
...	all other values are rejected

Table 9: Store

## 4.2 Restore

To reset the configuration of the valve to factory default settings a write access to the function "RestoreDefaultParameters" has to be performed.

Slot	Index	Name	Data Type	Access	Persis- tence	Value Range	Default
0	52	Restore Default Parameters	INT32	rw	N	INT32	0

Value table:

Value	Function
0x6C6F6164 ('load')	"RestoreDefaultParameters" function is called
...	all other values are rejected

Table 10: Restore

When the "RestoreDefaultParameters" function is started the configuration of the valve is reset to the factory default values. The new parameters are automatically stored in the internal nonvolatile memory of the valve. Because also the communication configuration of the valve is restored the valve performs a restart of the application program to reinitialize the communication interface. Therefore the "RestoreDefaultParameters" request is not acknowledged by the valve, because the communication configuration is changed immediately. The valve automatically restarts the PROFIBUS state machine and waits for the new parameterization and configuration from the master.

- ! A "RestoreDefaultParameters" may only be performed in a save machine state because all configuration changes like communication parameters or controller adjustments are set back to factory default.

## 5 PROFIBUS hardware and cabling

### 5.1 Complied hardware standards

The PROFIBUS Interface Hardware is successfully tested according testspecification for PROFIBUS slaves Version 2.0 of the PNO, Order No: 2.032.

## 5.2 Cabling of PROFIBUS Slaves

The use of 2-wire PROFIBUS cables is recommended to prevent parallel connection of the power supplies for the terminating resistors. The IEC 61158 specifies two kind of bus cables. Type B is no more up to date and should not be used any more.

Parameter	Cable (Type A)
Characteristic wave impedance ( $\Omega$ )	135 ... 165 bei 3 ... 20 MHz
Mutual capacitance (pF/m)	< 30
Loop resistance ( $\Omega$ /km)	< 110
Wire diameter (mm)	> 0,64
Wire cross-section (mm <sup>2</sup> )	> 0,34

Table 11: PROFIBUS cable Characteristics

## 5.3 Advice according Baude rates

At bitrates higher than 1500 kbit/s no stubs should be used. If the stubs are necessary, no termination resistors may be placed in this circuits. Cable stubs up to 1500 kbit/s should be in sum smaller than 6,6 m.

Cable lengths for different bitrates:

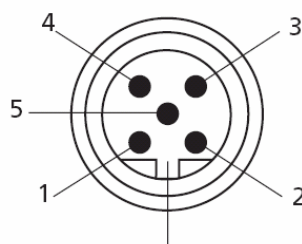
Supported bitrates (kBit/s)	Maximum cable length (m)
9,6	1200
19,2	1200
45,45	1200
93,75	1200
187,5	1200
500	400
1500	200
3000	100
6000	100
12000	100

Table 12: Bitrate/Cable length

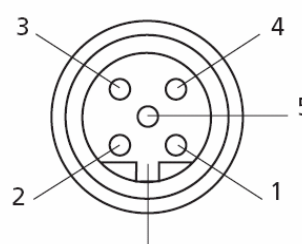
## 5.4 PROFIBUS connectors

The valve is equipped with two M12 (male, female) 5 pole PROFIBUS connectors, B-coded according to the IEC 61076-2-101.

X3 (male)



X4 (female)



Pin	Signal (X3, X4)	
1	Profi V+	Supply voltage for termination resistors
2	Profi A	Rx/Tx data -
3	Profi GND	supply voltage ground
4	Profi B	Rx/Tx data +
5	Shield	cable shield

Table 13: Pin Assignment

## 6 Object dictionary

- ! On request, we provide a GSD file. The GSD file is needed to import the communication specification into the PROFIBUS projecting system. It contains the supported functionalities and the predefined communication telegrams.

preliminary

Slot	Index	Short Name	Specifica- tion	Block Name	Parameter Name	Data Type	Access Level	Persistence	Value Range	Default
0	20	devvennam	DS408	Device	VendorName	STRING	ro	-		MOOG GmbH, Hanns-Klemm- Strasse 28, D- 71034 Boeblingen, Germany 2036
0	21	provenide	DIV	Pro	Vendor_ID	UINT16	ro	-	UINT16	
0	22	devver	DS408	Device	DeviceVersion	STRING	ro	-		
0	26	manhdwver	DS301	Device	ManufacturerHardwareVersion	STRING	ro	-		
0	28	sernum	DS408	Device	SerialNo	STRING	ro	-		
0	30	devmdlsc	DS408	Device	ModelDescription	STRING	ro	-		
0	32	devcodnum	DS408	Device	CodeNo	UINT16	rw	Y	UINT16	
0	33	devdsc	DS408	Device	Description	STRING	rw	Y		
0	36	deverrcod	DIV	Pro	ErrorCode	UINT16	ro	-	UINT16	
0	37	ctlwrd	DS408	Device	ControlWord	UINT16	rw	N	UINT16	
0	38	stswrd	DS408	Device	StatusWord	UINT16	ro	-	UINT16	
0	39	devmod	DS408	Device	DeviceMode	INT8	rw	N	1...4	DeviceModeDe- fault
0	40	ctlmod	DS408	Device	ControlMode	INT8	rw	N	-1...9	ControlModeDe- fault
0	41	locmod	DS408	Device	Local	INT8	rw	Y	-128...1	
0	42	prom2stpm	DIV	Pro	Master2SlaveTelegramProjectMSB	UINT32	rw	Y	UINT32	
0	43	prom2stpl	DIV	Pro	Master2SlaveTelegramProjectLSB	UINT32	rw	Y	UINT32	
0	44	pros2mtpm	DIV	Pro	Slave2MasterTelegramProjectMSB	UINT32	rw	Y	UINT32	
0	45	pros2mpl	DIV	Pro	Slave2MasterTelegramProjectLSB	UINT32	rw	Y	UINT32	
0	46	protelisel	DIV	Pro	TelegramSelection	UINT8	rw	Y	UINT8 16777216... 105700556	3
0	50	devcap	DS408	Device	Capability	UINT32	ro	-	8	1056964608
0	51	stopar	DS301	StoreParameters	SaveAllParameters	UINT32	rw	N	UINT32	1
0	52	rstpar	DS301	RestoreDefaultParam- eters	RestoreAllDefaultParameters	UINT32	rw	N	UINT32	1
0	202	pwdrly	DIV	System	PowerOnDelay	UINT8	rw	Y	0...10	
0	203	prspar	DIV	ValvePressureControl	SetpointParameter	UINT32	ro	-	UINT32	1669333264
0	204	spipar	DIV	ValvePositionControl	SetpointParameter	UINT32	ro	-	UINT32	1660944656
0	205	ctllocdef	DIV	Device	LocalControlWordDefault	UINT16	rw	Y	UINT16	263
0	206	ctlloc	DIV	Device	LocalControlWord	UINT16	rw	N	UINT16	LocalControl- WordDefault
0	207	devmoddef	DIV	Device	DeviceModeDefault	INT8	rw	Y	1...2	1
0	208	ctlmoddef	DIV	Device	ControlModeDefault	INT8	rw	Y	1...9	2
0	209	faisaftyp	DIV	ValveFailSafeWindow- Monitoring	Typ	INT8	ro	-	0...1	
0	210	faisafupp	DIV	ValveFailSafeWindow-	UpperLimit	INT16	ro	-	Lower-	16384



Monitoring									
0	211	faisaflow	DIV	ValveFailSafeWindow-Monitoring	LowerLimit	INT16	ro	-	Limit...32767
2	20	vlvtrdtlf	DS408	Valve_ActualValueConditioning	InterfaceNo	UINT8	rw	N	32768...UpperLimit
2	21	vlvtrdmax	DS408	Valve_ActualValueConditioning	MaxInterfaceNo	UINT8	ro	-	1...4
2	22	vlvtrdtyp	DS408	Valve_ActualValueConditioning	Type	INT8	rw	N	UINT8
2	23	trdprsmn	DS408	Valve_ActualValueConditioning	MinimumPressure	INT16	rw	N	INT8
2	25	trdprssigmin	DS408	Valve_ActualValueConditioning	MinimumTransducerSignal	INT16	rw	N	INT16
2	26	trdprsmx	DS408	Valve_ActualValueConditioning	MaximumPressure	INT16	rw	N	INT16
2	28	trdprssigmax	DS408	Valve_ActualValueConditioning	MaximumTransducerSignal	INT16	rw	N	INT16
2	29	trdpr sare	DS408	Valve_ActualValueConditioning	Area	INT16	rw	N	INT16
2	32	trdprsofs	DS408	Valve_ActualValueConditioning	PressureOffset	INT16	rw	N	INT16
2	83	vlvtrdval	DS408	Valve_ActualValueConditioning	ActualValue	INT16	ro	-	INT16
2	86	vlvtrdsgn	DS408	Valve_ActualValueConditioning	Sign	INT8	rw	N	-1...1
2	87	trdtlftval	DS408	Valve_ActualValueConditioning	ActualValue1	INT16	ro	-	INT16
2	88	trdtlftval	DS408	Valve_ActualValueConditioning	ActualValue2	INT16	ro	-	INT16
2	89	trdtlftval	DS408	Valve_ActualValueConditioning	ActualValue3	INT16	ro	-	INT16
2	90	trdtlftval	DS408	Valve_ActualValueConditioning	ActualValue3	INT16	ro	-	INT16
2	201	vlvtrdpar	DIV	Valve_ActualValueConditioning	TransducerPort	UINT32	rw	N	UINT32
21	1	spldemplt	DIV	ValvePositionControl	DemandValvePilot	INT16	ro	-	INT16
21	2	splvalplt	DIV	ValvePositionControl	ActualValvePilot	INT16	ro	-	INT16
21	21	splset	DS408	ValvePositionControl	Setpoint	INT16	rw	N	INT16
21	22	spluni	DS408	ValvePositionControl	Unit	UINT8	ro	-	UINT8
21	23	splprf	DS408	ValvePositionControl	Prefix	INT8	ro	-	INT8
21	24	spldem	DS408	ValvePositionControl	DemandValue	INT16	ro	-	INT16
21	25	spluni	DS408	ValvePositionControl	Unit	UINT8	ro	-	UINT8
21	26	splprf	DS408	ValvePositionControl	Prefix	INT8	ro	-	INT8

21	27	splpref	ValvePositionControl_DemandValueGene	ReferenceValue	INT16	INT16	16384
21	28	spluni	ValvePositionControl_Unit	Unit	UINT8	UINT8	0
21	29	splprf	ValvePositionControl_Prefix	Prefix	INT8	INT8	0
21	30	splsethld	ValvePositionControl_DemandValueGene	HoldSetPoint	INT16	INT16	0
21	31	spluni	ValvePositionControl_Unit	Unit	UINT8	UINT8	0
21	32	splprf	ValvePositionControl_Prefix	Prefix	INT8	INT8	0
21	33	spllimupp	ValvePositionControl_DemandValueGene	UpperLimit	INT16	LowerLimit...32767	16384
21	34	spluni	ValvePositionControl_Unit	Unit	UINT8	UINT8	0
21	35	splprf	ValvePositionControl_Prefix	Prefix	INT8	INT8	0
21	36	spllimlow	ValvePositionControl_DemandValueGene	LowerLimit	INT16	32768...UpperLimit	-16384
21	37	spluni	ValvePositionControl_Unit	Unit	UINT8	UINT8	0
21	38	splprf	ValvePositionControl_Prefix	Prefix	INT8	INT8	0
21	39	spldemfct	ValvePositionControl_DemandValueGene	Factor	UINT32	UINT32	65537
21	40	spldemofs	ValvePositionControl_DemandValueGene	Offset	INT16	INT16	0
21	41	spluni	ValvePositionControl_Unit	Unit	UINT8	UINT8	0
21	42	splprf	ValvePositionControl_Prefix	Prefix	INT8	INT8	0
21	43	splrmptyp	ValvePositionControl_DemandValueGene	Type	INT8	0...3	
21	44	splrmpacl	ValvePositionControl_DemandValueGene	AccelerationTime	UINT16	UINT16	3
21	45	timuni	ValvePositionControl_DemandValueGene	Unit	UINT8	UINT8	
21	46	splrmpaclprf	ValvePositionControl_DemandValueGene	AccelerationTime_Prefix	INT8	-4...0	-3
21	47	splrmpaclneg	ValvePositionControl_DemandValueGene	AccelerationTimeNegative	UINT16	UINT16	3
21	48	timuni	ValvePositionControl_DemandValueGene	Unit	UINT8	UINT8	
21	49	splrmpaclnegprf	ValvePositionControl_DemandValueGene	AccelerationTimeNegative_Prefix	INT8	-4...0	-3
21	50	splrmpaclpos	ValvePositionControl_DemandValueGene	AccelerationTimePositive	UINT16	UINT16	

## 6 Object dictionary

21	51	timuni	DS408	rator_Ramp	Unit	UINT8	ro	-	UINT8	3
21	52	splrmpdciposprf	DS408	ValvePositionControl_DemandValueGenerator_Ramp	AccelerationTimePositive_Prefix	INT8	rw	Y	-4...0	-3
21	53	splrmpdccl	DS408	ValvePositionControl_DemandValueGenerator_Ramp	DecelerationTime	UINT16	rw	Y	UINT16	3
21	54	timuni	DS408	-	Unit	UINT8	ro	-	UINT8	3
21	55	splrmpdciprf	DS408	ValvePositionControl_DemandValueGenerator_Ramp	DecelerationTime_Prefix	INT8	rw	Y	-4...0	-3
21	56	splrmpdcineg	DS408	ValvePositionControl_DemandValueGenerator_Ramp	DecelerationTimeNegative	UINT16	rw	Y	UINT16	3
21	57	timuni	DS408	-	Unit	UINT8	ro	-	UINT8	3
21	58	splrmpdcinegprf	DS408	ValvePositionControl_DemandValueGenerator_Ramp	DecelerationTimeNegative_Prefix	INT8	rw	Y	-4...0	-3
21	59	splrmpdcipos	DS408	ValvePositionControl_DemandValueGenerator_Ramp	DecelerationTimePositive	UINT16	rw	Y	UINT16	3
21	60	timuni	DS408	-	Unit	UINT8	ro	-	UINT8	3
21	61	splrmpdciposprf	DS408	ValvePositionControl_DemandValueGenerator_Ramp	DecelerationTimePositive_Prefix	INT8	rw	Y	-4...0	-3
21	86	spldirtyp	DS408	for_DirectionalDependentGain	Type	UINT8	rw	Y	0...1	
21	87	spldirfct	DS408	ValvePositionControl_DemandValueGenerator_Ramp	Factor	UINT32	rw	Y	UINT32	65537
21	96	splchrtyp	DS408	for_CharacteristicCompensation	Type	INT8	rw	Y	-1...0	
21	106	spldbdtyp	DS408	for_DeadbandCompensation	Type	INT8	rw	Y	0...2	
21	107	spldbdsida	DS408	ValvePositionControl_DemandValueGenerator_Aside	ASide	INT16	rw	Y	0...16384	

21	108	spluni	ra- tor_DeadbandCompens ation	DS408	Unit	rw	UINT8	UINT8	0
21	109	splprf	ValvePositionControl Prefix	DS408	Prefix	ro	INT8	INT8	0
21	110	spldbdsdb	ra- tor_DeadbandCompens ation	DS408	BSide	rw	INT16	0...16384	
21	111	spluni	ValvePositionControl	DS408	Unit	ro	UINT8	UINT8	0
21	112	splprf	ValvePositionControl Prefix	DS408	Prefix	ro	INT8	INT8	0
21	113	spldbdtrs	ra- tor_DeadbandCompens ation	DS408	Threshold	rw	INT16	0...16383	
21	114	spluni	ValvePositionControl	DS408	Unit	ro	UINT8	UINT8	0
21	115	splprf	ValvePositionControl Prefix	DS408	Prefix	ro	INT8	INT8	0
21	128	splzrocor	trol_DemandValueGene rator_ZeroCorrection	DS408	Offset	rw	INT16	INT16	0
21	129	spluni	ValvePositionControl	DS408	Unit	ro	UINT8	UINT8	0
21	130	splprf	ValvePositionControl	DS408	Prefix	ro	INT8	INT8	0
21	144	splval	ValvePositionControl	DS408	ActualValue	ro	INT16	INT16	0
21	145	spluni	ValvePositionControl	DS408	Unit	ro	UINT8	UINT8	0
21	146	splprf	ValvePositionControl	DS408	Prefix	ro	INT8	INT8	0
21	147	splctdvn	ValvePositionControl	DS408	ControlDeviation	ro	INT16	INT16	0
21	148	spluni	ValvePositionControl	DS408	Unit	ro	UINT8	UINT8	0
21	149	splprf	ValvePositionControl	DS408	Prefix	ro	INT8	INT8	0
21	150	splmontyp	ValvePositionCon- trol_ControlMonitoring	DS408	Type	rw	INT8	0...1	
21	151	splmonupp	ValvePositionCon- trol_ControlMonitoring	DS408	UpperThreshold	rw	INT16	INT16	512
21	152	spluni	ValvePositionControl	DS408	Unit	ro	UINT8	UINT8	0
21	153	splprf	ValvePositionControl	DS408	Prefix	ro	INT8	INT8	0
21	154	splmonlow	ValvePositionCon- trol_ControlMonitoring	DS408	LowerThreshold	rw	INT16	INT16	-512
21	155	spluni	ValvePositionControl	DS408	Unit	ro	UINT8	UINT8	0
21	156	splprf	ValvePositionControl	DS408	Prefix	ro	INT8	INT8	0
21	157	splmontim	ValvePositionCon- trol_ControlMonitoring	DS408	DelayTime	rw	UINT16	UINT16	30
21	158	timuni	-	DS408	Unit	ro	UINT8	UINT8	3
21	159	timprf	-	DS408	Prefix	ro	INT8	INT8	-3
21	231	splchrtbl	PositionCon- trol_DemandValueGene ra-	DIV	LookUpTable	rw	DOMAIN		

21	232	sp1chrtbl	DIV	for_CharacteristicComp ensation PositionCon- trol_DemandValueGene ra-	LookUpTable	INT16	rw	Y	INT16	
21	233	sp1chrtbl	DIV	for_CharacteristicComp ensation PositionCon- trol_DemandValueGene ra-	LookUpTable	INT16	rw	Y	INT16	
21	234	sp1chrtbl	DIV	for_CharacteristicComp ensation	LookUpTable	INT16	rw	Y	INT16	
22	21	prsrset	DS408	ValvePressureControl	Setpoint	INT16	rw	N	INT16	
22	22	prsrni	DS408	ValvePressureControl	Unit	UINT8	ro	-	UINT8	0
22	23	prsprf	DS408	ValvePressureControl	Prefix	INT8	ro	-	INT8	0
22	24	prsdem	DS408	ValvePressureCon- trol_DemandValueGene	Demand	INT16	ro	-	INT16	
22	25	prsrni	DS408	ValvePressureControl	Unit	UINT8	ro	-	UINT8	0
22	26	prsprf	DS408	ValvePressureControl	Prefix	INT8	ro	-	INT8	0
22	27	prsrref	DS408	ValvePressureCon- trol_DemandValueGene	ReferenceValue	INT16	rw	N	0...32767	400
22	28	prsrrefuni	DS408	ValvePressureCon- trol_DemandValueGene	Unit	UINT8	ro	-	UINT8	78
22	29	prsprf	DS408	ValvePressureControl	Prefix	INT8	ro	-	INT8	0
22	30	prsrsethld	DS408	ValvePressureCon- trol_DemandValueGene	HoldSetPoint	INT16	rw	Y	INT16	
22	31	prsrni	DS408	ValvePressureControl	Unit	UINT8	ro	-	UINT8	0
22	32	prsprf	DS408	ValvePressureControl	Prefix	INT8	ro	-	INT8	0
22	33	prsrlimupp	DS408	ValvePressureCon- trol_DemandValueGene	UpperLimit	Limit...32767	rw	Y	Limit...32767	16384
22	34	prsrni	DS408	ValvePressureControl	Unit	UINT8	ro	-	UINT8	0
22	35	prsprf	DS408	ValvePressureControl	Prefix	INT8	ro	-	INT8	0
22	36	prsrlimlow	DS408	ValvePressureCon- trol_DemandValueGene	LowerLimit	32768...Upp	rw	Y	erLimit	-16384
22	37	prsrni	DS408	ValvePressureControl	Unit	UINT8	ro	-	UINT8	0
22	38	prsprf	DS408	ValvePressureControl	Prefix	INT8	ro	-	INT8	0

22	39	prsdemfct	DS408	ValvePressureControl_DemandValueGenerator_Scaling	Factor	UINT32	rw	Y	UINT32	65537
22	40	prsdemofs	DS408	ValvePressureControl_DemandValueGenerator_Scaling	Offset	INT16	rw	Y	INT16	
22	41	prsun1	DS408	ValvePressureControl	Unit	UINT8	ro	-	UINT8	0
22	42	prsprf	DS408	ValvePressureControl	Prefix	INT8	ro	-	INT8	0
22	43	prsmptyp	DS408	ValvePressureControl_DemandValueGenerator_Ramp	Type	INT8	rw	Y	0...3	
22	44	prsmppacl	DS408	ValvePressureControl_DemandValueGenerator_Ramp	AccelerationTime	UINT16	rw	Y	UINT16	
22	45	timuni	DS408	-	Unit	UINT8	ro	-	UINT8	3
22	46	prsmppaclprf	DS408	ValvePressureControl_DemandValueGenerator_Ramp	AccelerationTime_Prefix	INT8	rw	Y	-4...0	-3
22	47	prsmppaclneg	DS408	ValvePressureControl_DemandValueGenerator_Ramp	AccelerationTimeNegative	UINT16	rw	Y	UINT16	
22	48	timuni	DS408	-	Unit	UINT8	ro	-	UINT8	3
22	49	prsmppaclnegprf	DS408	ValvePressureControl_DemandValueGenerator_Ramp	AccelerationTimeNegative_Prefix	INT8	rw	Y	-4...0	-3
22	50	prsmppaclpos	DS408	ValvePressureControl_DemandValueGenerator_Ramp	AccelerationTimePositive	UINT16	rw	Y	UINT16	
22	51	timuni	DS408	-	Unit	UINT8	ro	-	UINT8	3
22	52	prsmppaclposprf	DS408	ValvePressureControl_DemandValueGenerator_Ramp	AccelerationTimePositive_Prefix	INT8	rw	Y	-4...0	-3
22	53	prsmppdcl	DS408	ValvePressureControl_DemandValueGenerator_Ramp	DecelerationTime	UINT16	rw	Y	UINT16	
22	54	timuni	DS408	-	Unit	UINT8	ro	-	UINT8	3
22	55	prsmppdclprf	DS408	ValvePressureControl_DemandValueGenerator_Ramp	DecelerationTime_Prefix	INT8	rw	Y	-4...0	-3
22	56	prsmppdclneg	DS408	ValvePressureControl_DemandValueGenerator_Ramp	DecelerationTimeNegative	UINT16	rw	Y	UINT16	
22	57	timuni	DS408	-	Unit	UINT8	ro	-	UINT8	3
22	58	prsmppdclnegprf	DS408	ValvePressureControl_DemandValueGenerator_Ramp	DecelerationTimeNegative_Prefix	INT8	rw	Y	-4...0	-3
22	59	prsmppdclpos	DS408	ValvePressureControl	DecelerationTimePositive	UINT16	rw	Y	UINT16	

22	60	timuni	DS408	trol_DemandValueGenerator_Ramp	Unit	UINT8	ro	-	UINT8	3
22	61	prsmprdcposprf	DS408	ValvePressureControl_Ramp	DecelerationTimePositive_Prefix	INT8	rw	Y	-4...0	-3
22	144	prsva1	DS408	ValvePressureControl	ActualValue	INT16	ro	-	INT16	0
22	145	prsu1	DS408	ValvePressureControl	Unit	UINT8	ro	-	UINT8	0
22	146	prsprf	DS408	ValvePressureControl	Prefix	INT8	ro	-	INT8	0
22	147	prscldvn	DS408	ValvePressureControl	ControlDeviation	INT16	ro	-	INT16	0
22	148	prsu1	DS408	ValvePressureControl	Unit	UINT8	ro	-	UINT8	0
22	149	prsprf	DS408	ValvePressureControl	Prefix	INT8	ro	-	INT8	0
22	150	prsmontyp	DS408	ValvePressureControl	Type	INT8	rw	Y	0...1	
22	151	prsmontyp	DS408	ValvePressureControl	UpperThreshold	INT16	rw	Y	INT16	512
22	152	prsu1	DS408	ValvePressureControl	Unit	UINT8	ro	-	UINT8	0
22	153	prsprf	DS408	ValvePressureControl	Prefix	INT8	ro	-	INT8	0
22	154	prsmontyp	DS408	ValvePressureControl	LowerThreshold	INT16	rw	Y	INT16	-512
22	155	prsu1	DS408	ValvePressureControl	Unit	UINT8	ro	-	UINT8	0
22	156	prsprf	DS408	ValvePressureControl	Prefix	INT8	ro	-	INT8	0
22	157	prsmontim	DS408	ValvePressureControl	DelayTime	UINT16	rw	Y	UINT16	30
22	158	timuni	DS408	Unit	Unit	UINT8	ro	-	UINT8	3
22	159	timprf	DS408	Prefix	Prefix	INT8	ro	-	INT8	-3
64	0	promodide	DIV	PROFIBUSModuleIdentifier	PROFIBUSModuleIdentifier	UINT8	rw	Y	1...126	126
64	1	probrdr	DIV	PROFIBUSBitrate	PROFIBUSBitrate	UINT32	ro	-	0...1200000	
64	2	procfklen	DIV	Configuration_Telegram_Length	Configuration_Telegram_Length	UINT8	ro	-	0	
64	3	procfgio	DIV	ConfigurationTelegramBytes	ConfigurationTelegramBytes	UINT8	ro	-	UINT8	
64	9	procfgio	DIV	ConfigurationTelegramBytes	ConfigurationTelegramBytes	UINT8	ro	-	UINT8	
64	10	propmchn	DIV	ParameterChannelActive	ParameterChannelActive	UINT8	rw	Y	0...1	
64	11	vpcsts	DIV	VPC3+b_Status	VPC3+b_Status	UINT16	ro	-	UINT16	
64	12	prodvpv1mod	DIV	DPV1Mode	DPV1Mode	UINT8	ro	-	0...1	
64	13	ideobj	DIV	VendorId	VendorId	UINT32	ro	-	UINT32	2036
64	14	ideobj	DIV	ProductCode	ProductCode	UINT32	ro	-	UINT32	
64	15	ideobj	DIV	RevisionNumber	RevisionNumber	UINT32	ro	-	UINT32	
64	16	ideobj	DIV	SerialNumber	SerialNumber	UINT32	ro	-	UINT32	
64	17	prosigar	DIV	SignalParameterSelection	SignalParameterSelection	UINT32	rw	Y	UINT32	
64	33	prosigar	DIV	SignalParameterSelection	SignalParameterSelection	UINT32	rw	Y	UINT32	
64	33	pronode	DIV	PROFIBUSActualNodeIdentifier	PROFIBUSActualNodeIdentifier	UINT8	ro	-	1...126	126
64	34	progt	DIV	PROFIBUSGlobalControlTelegram	PROFIBUSGlobalControlTelegram	UINT8	ro	-	UINT8	
66	1	cmpprstyp	DIV	PressureControllerType	PressureControllerType	UINT8	ro	-	UINT8	
66	16	cmpprstyp	DIV	PressureControllerType	PressureControllerType	UINT8	rw	Y	UINT8	
66	17	cmpprsif	DIV	PressureControllerActiveTrans-	PressureControllerActiveTrans-	INT8	rw	Y	1...4	1

66	32	cmpprstf	DIV	ValvePressureControl	PressureControllerActiveTransducerInterface	INT8	rw	Y	1..4	1
66	33	cmpprstfb	DIV	ValvePressureControl	PressureControllerTransducerInterfaceAreaB	INT8	rw	Y	0..4	
66	48	cmpprstfbb	DIV	ValvePressureControl	PressureControllerTransducerInterfaceAreaB	INT8	rw	Y	0..4	
66	49	cmpprsprs	DIV	ValvePressureControl	SystemPressure	INT16	rw	Y	INT16	
66	64	cmpprsprs	DIV	ValvePressureControl	SystemPressure	INT16	rw	Y	INT16	
66	65	cmpprsprb	DIV	ValvePressureControl	ReferencePressure	INT16	rw	Y	INT16	
66	80	cmpprsprb	DIV	ValvePressureControl	ReferencePressure	INT16	rw	Y	INT16	
66	81	cmpprschy	DIV	ValvePressureControl	HydraulicCapacity	FLOAT32	rw	Y	FLOAT32	
66	96	cmpprschy	DIV	ValvePressureControl	HydraulicCapacity	FLOAT32	rw	Y	FLOAT32	
66	97	cmpprsmmp	DIV	ValvePressureControl	RampSlope	UINT16	rw	Y	UINT16	
66	112	cmpprsmmp	DIV	ValvePressureControl	RampSlope	UINT16	rw	Y	UINT16	
66	113	cmpprspgn	DIV	ValvePressureControl	ProportionalGain	FLOAT32	rw	Y	Pres-sureNullCo n-stantF32...+ inv	
66	128	cmpprspgn	DIV	ValvePressureControl	ProportionalGain	FLOAT32	rw	Y	Pres-sureNullCo n-stantF32...+ inv	
66	129	cmpprspmt	DIV	ValvePressureControl	ProportionalGainTimeConstant	FLOAT32	rw	Y	Pres-sureNullCo n-stantF32...+ inv	
66	144	cmpprspmt	DIV	ValvePressureControl	ProportionalGainTimeConstant	FLOAT32	rw	Y	Pres-sureNullCo n-stantF32...+ inv	
66	145	cmpprsign	DIV	ValvePressureControl	IntegratorGain	FLOAT32	rw	Y	Pres-sureNullCo n-stantF32...+ inv	
66	160	cmpprsign	DIV	ValvePressureControl	IntegratorGain	FLOAT32	rw	Y	Pres-sureNullCo n-stantF32...+ inv	
66	161	cmpprsigf	DIV	ValvePressureControl	IntegratorFactor	FLOAT32	rw	Y	FLOAT32	
66	176	cmpprsigf	DIV	ValvePressureControl	IntegratorFactor	FLOAT32	rw	Y	FLOAT32	



## 6 Object dictionary

66	177	cmpprsicr	DIV	ValvePressureControl	IntegratorControlRange	INT16	rw	Y	0...32767	163
66	192	cmpprsicr	DIV	ValvePressureControl	IntegratorControlRange	INT16	rw	Y	0...32767	163
									Pres-sureNullCo	
									n-	
									stantF32...+	
									inv	
66	193	cmpprsdgn	DIV	ValvePressureControl	DifferentiatorGain	FLOAT32	rw	Y	Pres-sureNullCo	
									n-	
									stantF32...+	
									inv	
66	208	cmpprsdgn	DIV	ValvePressureControl	DifferentiatorGain	FLOAT32	rw	Y	Pres-sureNullCo	
									n-	
									stantF32...+	
									inv	
66	225	cmpprsdtn	DIV	ValvePressureControl	DifferentiatorT1	FLOAT32	rw	Y	Pres-sureNullCo	
									n-	
									stantF32...+	
									inv	
66	240	cmpprsdtn	DIV	ValvePressureControl	DifferentiatorT1	FLOAT32	rw	Y	stantF32...+	
66	241	cmpprsdtn	DIV	ValvePressureControl	DifferentiatorT1	FLOAT32	rw	Y	stantF32...+	
66	242	cmpprsdtn	DIV	ValvePressureControl	DifferentiatorT1	FLOAT32	rw	Y	stantF32...+	
66	243	cmpprsdtn	DIV	ValvePressureControl	DifferentiatorT1	FLOAT32	rw	Y	stantF32...+	
66	246	prsdtnum	DIV	ValvePressureControl	ActiveParameterSetNumber	UINT8	rw	Y	1...16	1
66	247	cmpprsdtn	DIV	ValvePressureControl	ControllerOutput	INT16	ro	-	INT16	
									0.000000...	#####
66	248	cmpprsdtn	DIV	ValvePressureControl	CylinderPistonDiameter	FLOAT32	rw	Y	0.000000...	
									CylinderPis-tonDiameter	
66	249	cmpprsdtn	DIV	ValvePressureControl	CylinderRodDiameterA	FLOAT32	rw	Y	0.000000...	
									CylinderPis-tonDiameter	
66	250	cmpprsdtn	DIV	ValvePressureControl	CylinderRodDiameterB	FLOAT32	rw	Y	0.000000...	
									LowerOut-put-Limit...32767	Pressure-FullScaleCon-stantPositive
67	49	cmpprsdtn	DIV	ValvePressureControl	UpperOutputLimit	INT16	rw	Y	LowerOut-put-Limit...32767	Pressure-FullScaleCon-stantPositive
									32768...UpperOutput-Limit	Pressure-FullScaleCon-stantNegative
67	64	cmpprsdtn	DIV	ValvePressureControl	UpperOutputLimit	INT16	rw	Y	32768...UpperOutput-Limit	Pressure-FullScaleCon-stantNegative
									32768...UpperOutput-Limit	Pressure-FullScaleCon-stantNegative
67	65	cmpprsdtn	DIV	ValvePressureControl	LowerOutputLimit	INT16	rw	Y	32768...UpperOutput-Limit	Pressure-FullScaleCon-stantNegative
67	80	cmpprsdtn	DIV	ValvePressureControl	LowerOutputLimit	INT16	rw	Y	32768...UpperOutput-Limit	Pressure-FullScaleCon-stantNegative



## 6 Object dictionary

71	55	vars08	DIV	Eventhandler	INTEGER8	INT8	rw	N	INT8
71	56	vars16	DIV	Eventhandler	INTEGER16	INT16	rw	N	INT16
71	63	vars16	DIV	Eventhandler	INTEGER16	INT16	rw	N	INT16
71	64	vars32	DIV	Eventhandler	INTEGER32	INT32	rw	N	INT32
71	71	vars32	DIV	Eventhandler	INTEGER32	INT32	rw	N	INT32
71	72	varu08	DIV	Eventhandler	UNSIGNED8	UINT8	rw	N	UINT8
71	79	varu08	DIV	Eventhandler	UNSIGNED8	UINT8	rw	N	UINT8
71	80	varu16	DIV	Eventhandler	UNSIGNED16	UINT16	rw	N	UINT16
71	87	varu16	DIV	Eventhandler	UNSIGNED16	UINT16	rw	N	UINT16
71	88	varu32	DIV	Eventhandler	UNSIGNED32	UINT32	rw	N	UINT32
71	95	varu32	DIV	Eventhandler	UNSIGNED32	UINT32	rw	N	UINT32
72	1	devmdlurl	DS408	Device	ModelURL	STRING	ro	-	
72	2	devprmcod	DS408	Device	ParameterSetCode	UINT8	rw	Y	0...254
72	10	cpusup	DIV	Hard-ware_DiagnosticData	CpuSupplyVoltage	UINT16	ro	-	UINT16
72	11	pwrsup	DIV	Hard-ware_DiagnosticData	PowerSupplyVoltage	UINT16	ro	-	UINT16
72	12	pobtmp	DIV	Hard-ware_DiagnosticData	PcbTemperature	INT16	ro	-	INT16
72	24	optim	DIV	Hard-ware_DiagnosticData	Operating Time	UINT32	ro	-	UINT32
72	25	optim	DIV	Hard-ware_DiagnosticData	Operating Time	UINT32	ro	-	UINT32
73	1	locmodule	DIV	Local_Can	ModuleIdentifier	UINT8	rw	Y	1...127
73	2	locbdr	DIV	Local_Can	Bitrate	UINT32	rw	Y	0...1000000
73	3	locsm	DIV	Local_Can	StartRemoteNode	UINT8	rw	N	UINT8
73	4	locrempar	DIV	LocalCAN	RemoteParameter	UINT32	rw	N	UINT32
73	5	locremadr	DIV	LocalCAN	RemoteParameterAddress	UINT32	rw	N	UINT32
73	6	locremmod	DIV	LocalCAN	RemoteNodeId	UINT8	rw	N	1...127
73	7	locremtrn	DIV	LocalCAN	RemoteTransmission	INT8	rw	N	-1...2
73	8	locpdr cob	DIV	LocalCAN	1stReceivePdo_CobIdUsedByPdo	UINT32	rw	Y	1...2147485
73	9	locpdr cob	DIV	LocalCAN	2ndReceivePdo_CobIdUsedByPdo	UINT32	rw	Y	695
73	10	locpdr cob	DIV	LocalCAN	3rdReceivePdo_CobIdUsedByPdo	UINT32	rw	Y	1...2147485
73	11	locpdr cob	DIV	LocalCAN	4thReceivePdo_CobIdUsedByPdo	UINT32	rw	Y	695
73	12	locpdr trn	DIV	LocalCAN	1stReceivePdo_TransmissionType	UINT8	rw	Y	1407
73	13	locpdr trn	DIV	LocalCAN	2ndReceivePdo_TransmissionType	UINT8	rw	Y	255
73	14	locpdr trn	DIV	LocalCAN	3rdReceivePdo_TransmissionType	UINT8	rw	Y	255
73	15	locpdr trn	DIV	LocalCAN	4thReceivePdo_TransmissionType	UINT8	rw	Y	255
73	16	locpdr trm	DIV	LocalCAN	1stReceivePdo_EventTimer	UINT16	rw	Y	UINT16
73	17	locpdr trm	DIV	LocalCAN	2ndReceivePdo_EventTimer	UINT16	rw	Y	UINT16
73	18	locpdr trm	DIV	LocalCAN	3rdReceivePdo_EventTimer	UINT16	rw	Y	UINT16
73	19	locpdr trm	DIV	LocalCAN	4thReceivePdo_EventTimer	UINT16	rw	Y	UINT16

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73	20	lcpdrmap	DIV	LocalCAN	ReceivePdoMappingParameter_PdoMappingForTheNthApplicationObjectToBeMapped	UINT32	rw	Y	UINT32
73	27	lcpdrmap	DIV	LocalCAN	ReceivePdoMappingParameter_PdoMappingForTheNthApplicationObjectToBeMapped	UINT32	rw	Y	UINT32
73	28	lcpdrmap	DIV	LocalCAN	ReceivePdoMappingParameter_PdoMappingForTheNthApplicationObjectToBeMapped	UINT32	rw	Y	UINT32
73	35	lcpdrmap	DIV	LocalCAN	ReceivePdoMappingParameter_PdoMappingForTheNthApplicationObjectToBeMapped	UINT32	rw	Y	UINT32
73	36	lcpdrmap	DIV	LocalCAN	ReceivePdoMappingParameter_PdoMappingForTheNthApplicationObjectToBeMapped	UINT32	rw	Y	UINT32
73	41	lcpdrmap	DIV	LocalCAN	ReceivePdoMappingParameter_PdoMappingForTheNthApplicationObjectToBeMapped	UINT32	rw	Y	UINT32
73	42	lcpdrmap	DIV	LocalCAN	ReceivePdoMappingParameter_PdoMappingForTheNthApplicationObjectToBeMapped	UINT32	rw	Y	UINT32
73	49	lcpdrmap	DIV	LocalCAN	ReceivePdoMappingParameter_PdoMappingForTheNthApplicationObjectToBeMapped	UINT32	rw	Y	UINT32
73	50	lcpdrmapnum	DIV	LocalCAN	1stReceivePdoMapping_NumberOfMappedApplicationObjectsInPdo	UINT8	rw	Y	0...8
73	51	lcpdrmapnum	DIV	LocalCAN	2ndReceivePdoMapping_NumberOfMappedApplicationObjectsInPdo	UINT8	rw	Y	0...8
73	52	lcpdrmapnum	DIV	LocalCAN	3rdReceivePdoMapping_NumberOfMappedApplicationObjectsInPdo	UINT8	rw	Y	0...8
73	53	lcpdrmapnum	DIV	LocalCAN	4thReceivePdoMapping_NumberOfMappedApplicationObjectsInPdo	UINT8	rw	Y	0...8
73	54	lcpdrcob	DIV	LocalCAN	1stTransmitPdo_CobIdUsedByPdo	UINT32	rw	Y	0...8 1...2147485 695 511
73	55	lcpdrcob	DIV	LocalCAN	2ndTransmitPdo_CobIdUsedByPdo	UINT32	rw	Y	0...8 1...2147485 695 767
73	56	lcpdrcob	DIV	LocalCAN	3rdTransmitPdo_CobIdUsedByPdo	UINT32	rw	Y	0...8 1...2147485 695 1023
73	57	lcpdrcob	DIV	LocalCAN	4thTransmitPdo_CobIdUsedByPdo	UINT32	rw	Y	0...8 1...2147485 695 1279
73	58	lcpdtrn	DIV	LocalCAN	1stTransmitPdo_TransmissionType	UINT8	rw	Y	UINT8 255
73	59	lcpdtrn	DIV	LocalCAN	2ndTransmitPdo_TransmissionType	UINT8	rw	Y	UINT8 255
73	60	lcpdtrn	DIV	LocalCAN	3rdTransmitPdo_TransmissionType	UINT8	rw	Y	UINT8 255
73	61	lcpdtrn	DIV	LocalCAN	4thTransmitPdo_TransmissionType	UINT8	rw	Y	UINT8 255
73	62	lcpdtrnman	DIV	Local_CAN	1stLocalCANTransmitPdoManufacturerTransmissionType	UINT8	rw	Y	UINT8
73	63	lcpdtrnman	DIV	Local_CAN	2ndLocalCANTransmitPdoManufacturerTransmissionType	UINT8	rw	Y	UINT8

73	64	locpdtrman	DIV	Local_Can	userTransmissionType	UINT8	rw	Y	UINT8
73	65	locpdtrman	DIV	Local_Can	3rdLocalCANTransmitPdoManufact	UINT8	rw	Y	UINT8
73	66	locpdtrinh	DIV	LocalCAN	urTransmissionType	UINT16	rw	Y	UINT16
73	67	locpdtrinh	DIV	LocalCAN	1stTransmitPdo_InhibitTime	UINT16	rw	Y	UINT16
73	68	locpdtrinh	DIV	LocalCAN	2ndTransmitPdo_InhibitTime	UINT16	rw	Y	UINT16
73	69	locpdtrinh	DIV	LocalCAN	3rdTransmitPdo_InhibitTime	UINT16	rw	Y	UINT16
73	70	locpdtrinh	DIV	LocalCAN	4thTransmitPdo_InhibitTime	UINT16	rw	Y	UINT16
73	71	locpdttim	DIV	LocalCAN	1stTransmitPdo_EventTimer	UINT16	rw	Y	UINT16
73	72	locpdttim	DIV	LocalCAN	2ndTransmitPdo_EventTimer	UINT16	rw	Y	UINT16
73	73	locpdttim	DIV	LocalCAN	3rdTransmitPdo_EventTimer	UINT16	rw	Y	UINT16
73	74	locpdttim	DIV	LocalCAN	4thTransmitPdo_EventTimer	UINT16	rw	Y	UINT16
73	74	locpdttim	DIV	LocalCAN	TransmitPdoMappingParameter_PdoMappingForTheNthApplicationObjectToBeMapped	UINT32	rw	Y	UINT32
73	81	locpdttmap	DIV	LocalCAN	TransmitPdoMappingParameter_PdoMappingForTheNthApplicationObjectToBeMapped	UINT32	rw	Y	UINT32
73	82	locpdttmap	DIV	LocalCAN	TransmitPdoMappingParameter_PdoMappingForTheNthApplicationObjectToBeMapped	UINT32	rw	Y	UINT32
73	89	locpdttmap	DIV	LocalCAN	TransmitPdoMappingParameter_PdoMappingForTheNthApplicationObjectToBeMapped	UINT32	rw	Y	UINT32
73	90	locpdttmap	DIV	LocalCAN	TransmitPdoMappingParameter_PdoMappingForTheNthApplicationObjectToBeMapped	UINT32	rw	Y	UINT32
73	97	locpdttmap	DIV	LocalCAN	TransmitPdoMappingParameter_PdoMappingForTheNthApplicationObjectToBeMapped	UINT32	rw	Y	UINT32
73	98	locpdttmap	DIV	LocalCAN	TransmitPdoMappingParameter_PdoMappingForTheNthApplicationObjectToBeMapped	UINT32	rw	Y	UINT32
73	105	locpdttmap	DIV	LocalCAN	TransmitPdoMappingParameter_PdoMappingForTheNthApplicationObjectToBeMapped	UINT32	rw	Y	UINT32
73	106	locpdttmapnum	DIV	LocalCAN	1stTransmitPdoMapping_NumberOfMappedApplicationObjectsInPdo	UINT8	rw	Y	0...8
73	107	locpdttmapnum	DIV	LocalCAN	2ndTransmitPdoMapping_NumberOfMappedApplicationObjectsInPdo	UINT8	rw	Y	0...8
73	108	locpdttmapnum	DIV	LocalCAN	3rdTransmitPdoMapping_NumberOfMappedApplicationObjectsInPdo	UINT8	rw	Y	0...8
73	109	locpdttmapnum	DIV	LocalCAN	4thTransmitPdoMapping_NumberOfMappedApplicationObjectsInPdo	UINT8	rw	Y	0...8
74	1	an0val	DIV	AnalogueInput0	ActualValue	INT16	ro	-	INT16
74	2	an0typ	DIV	AnalogueInput0	InputType	INT8	rw	Y	INT8

74	3	an1val	DIV	AnalogueInput1	ActualValue	INT16	ro	-	INT16	
74	4	an1typ	DIV	AnalogueInput1	InputType	INT8	rw	Y	INT8	
74	5	da0ref	DIV	AnalogueOutput0	Scaling	INT16	rw	Y	INT16	16384
74	6	da0ref	DIV	AnalogueOutput0	Scaling	INT16	rw	Y	INT16	16384
74	7	da0ref	DIV	AnalogueOutput1	Scaling	INT16	rw	Y	INT16	0
74	8	da1ref	DIV	AnalogueOutput1	Scaling	INT16	rw	Y	INT16	16384
74	9	da1ref	DIV	AnalogueOutput1	Scaling	INT16	rw	Y	INT16	16384
74	10	da1ref	DIV	AnalogueOutput1	Scaling	INT16	rw	Y	INT16	0
74	14	prstrd	DIV	PressureTransducer	Value	INT16	ro	-	INT16	
75	1	an2val	DIV	AnalogueInput2	ActualValue	INT16	ro	-	INT16	
75	2	an2typ	DIV	AnalogueInput2	InputType	INT8	rw	Y	INT8	
75	3	an2mon	DIV	AnalogueInput2	MonitoringCurrent	UINT8	rw	Y	0...1	
75	4	an3val	DIV	AnalogueInput3	ActualValue	INT16	ro	-	INT16	
75	5	an3typ	DIV	AnalogueInput3	InputType	INT8	rw	Y	INT8	
75	6	an3mon	DIV	AnalogueInput3	MonitoringCurrent	UINT8	rw	Y	0...1	
75	7	an4val	DIV	AnalogueInput4	ActualValue	INT16	ro	-	INT16	
75	8	an4typ	DIV	AnalogueInput4	InputType	INT8	rw	Y	INT8	
75	9	an4mon	DIV	AnalogueInput4	MonitoringCurrent	UINT8	rw	Y	0...1	
75	10	extlvdval	DIV	ExternallVDT	ActualValue	INT16	ro	-	INT16	
75	11	extlvdref	DIV	ExternallVDT	CustomerScalingFactorNumerator	INT16	rw	N	INT16	16384
					CustomerScalingFactorDenominator					
75	12	extlvdref	DIV	ExternallVDT	CustomerScalingOffset	INT16	rw	N	INT16	16384
75	13	extlvdref	DIV	ExternallVDT	CustomerScalingOffset	INT16	rw	N	INT16	0

For detailed description of the valve parameters and functions refer to the "PROFIBUS - DP Profile, Fluid Power Technology, v1.5".

## 7 Literature

### **PROFIBUS - DP Profile, Fluid Power Technology, v1.5**

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### **Testspecification for PROFIBUS slaves Version 2.0**

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### **Profile Fluid Power Technology**

#### **Proportional Valves and Hydrostatic Transmissions**

#### **Version 1.5**

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